



# CS F211: DATA STRUCTURES & ALGORITHMS

## (2<sup>ND</sup> SEMESTER 2024-25)

### TREE ADT

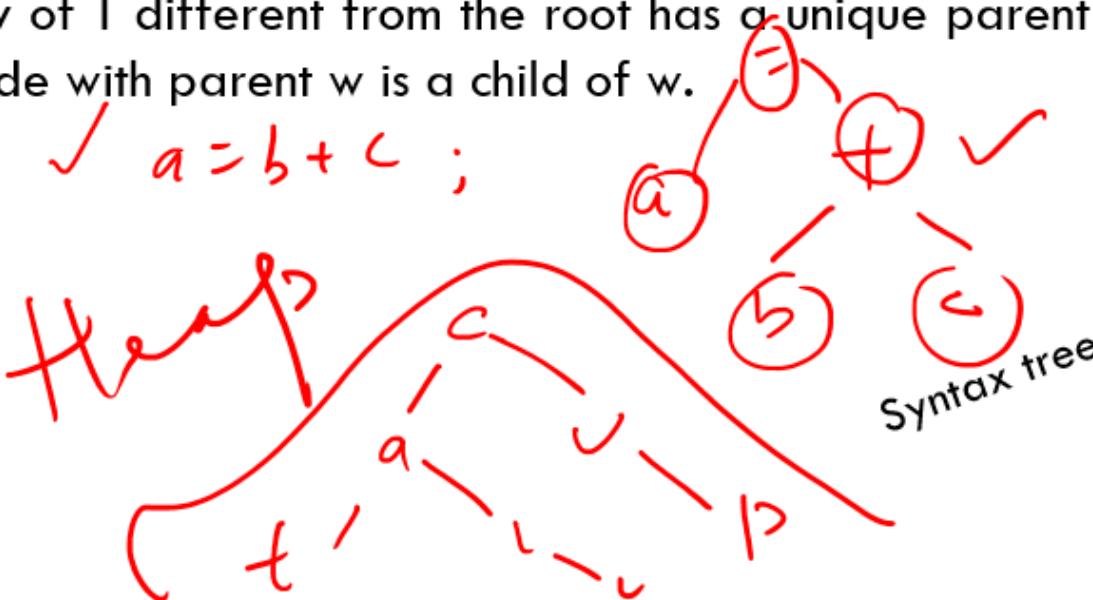
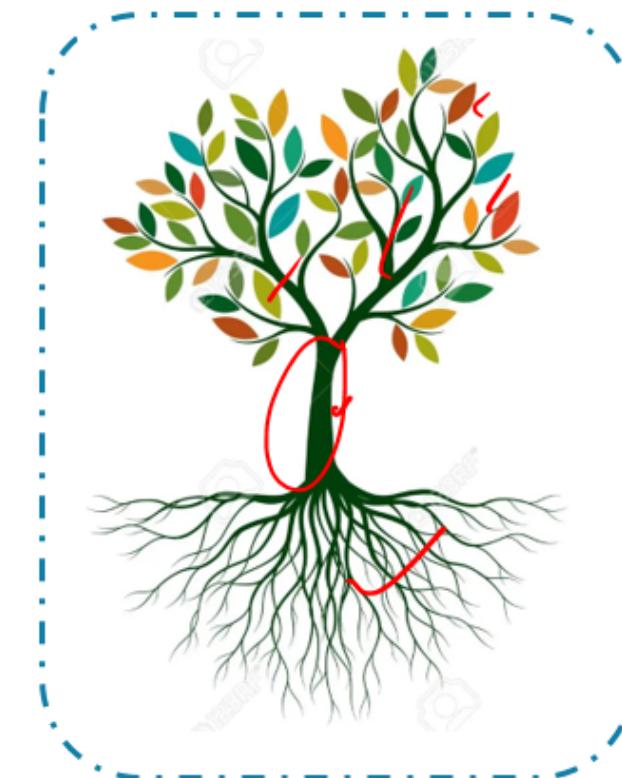
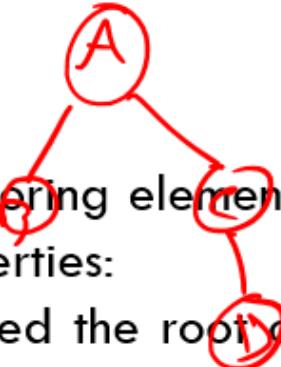
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# TREES: NON-LINEAR DATA STRUCTURES

- In computer science, what is a tree?

Formally, we define tree  $T$  to be a set of nodes storing elements in a **parent-child relationship** with the following properties:

- If  $T$  is nonempty, it has a special node, called the **root** of  $T$ , that has no parent.
- Each node  $v$  of  $T$  different from the root has a unique parent node  $w$ ; every node with parent  $w$  is a child of  $w$ .



Applications?

File  
Database  
Network  
Hierarchical storage

# TREE TERMINOLOGIES AND PROPERTIES

Root: ???

Internal node: ???

External node: ???

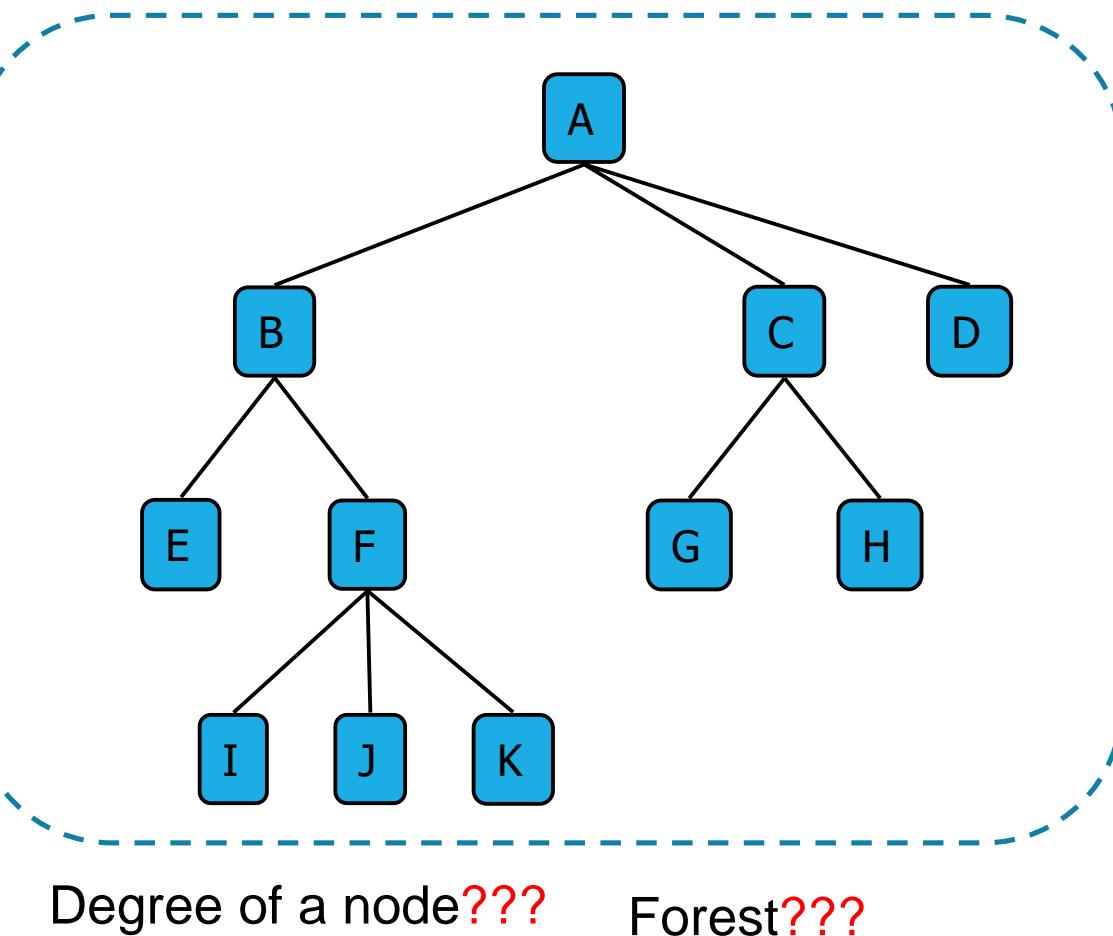
Ancestors of a node: ???

Level of a node or Depth of a node:  
???

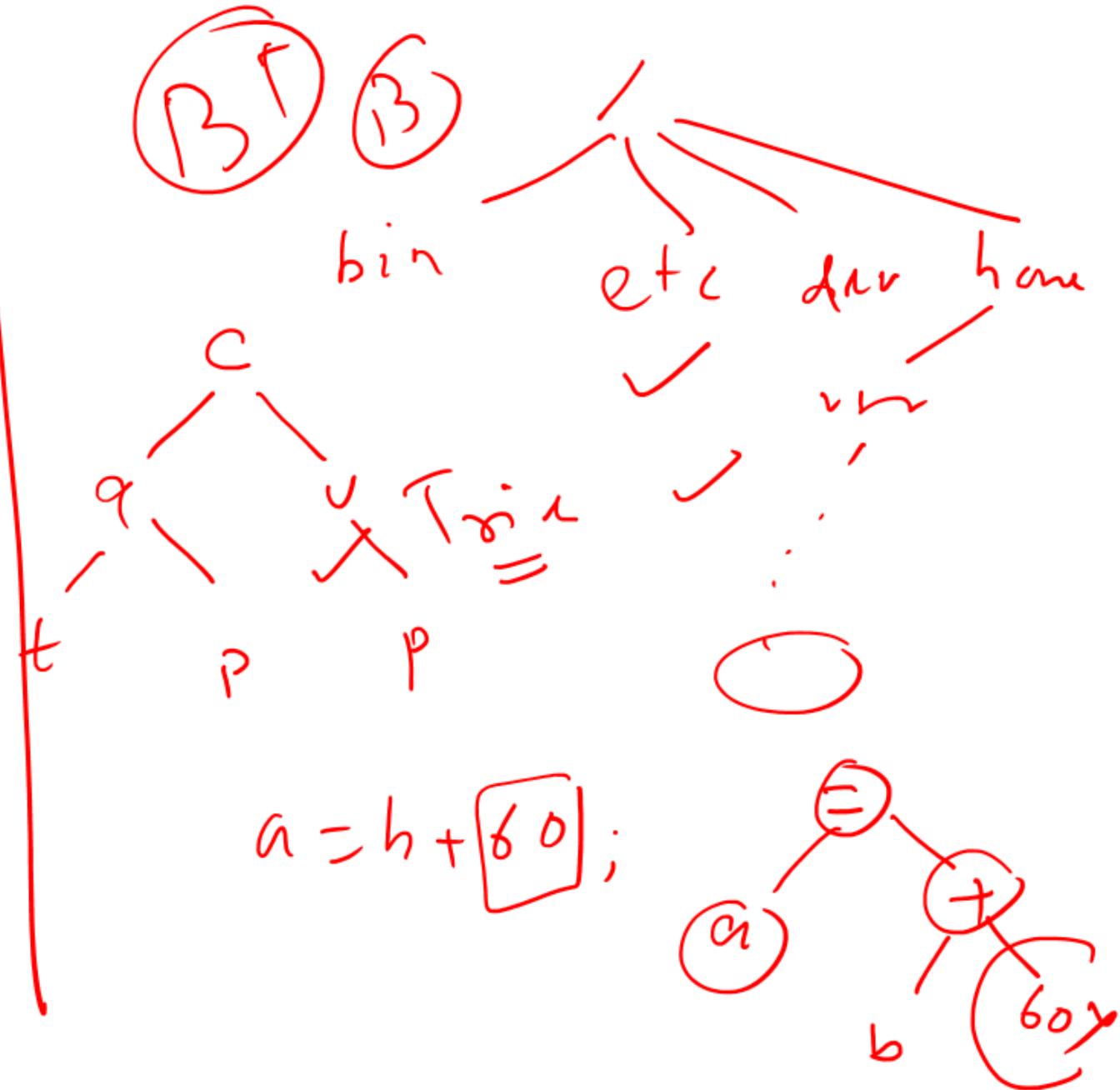
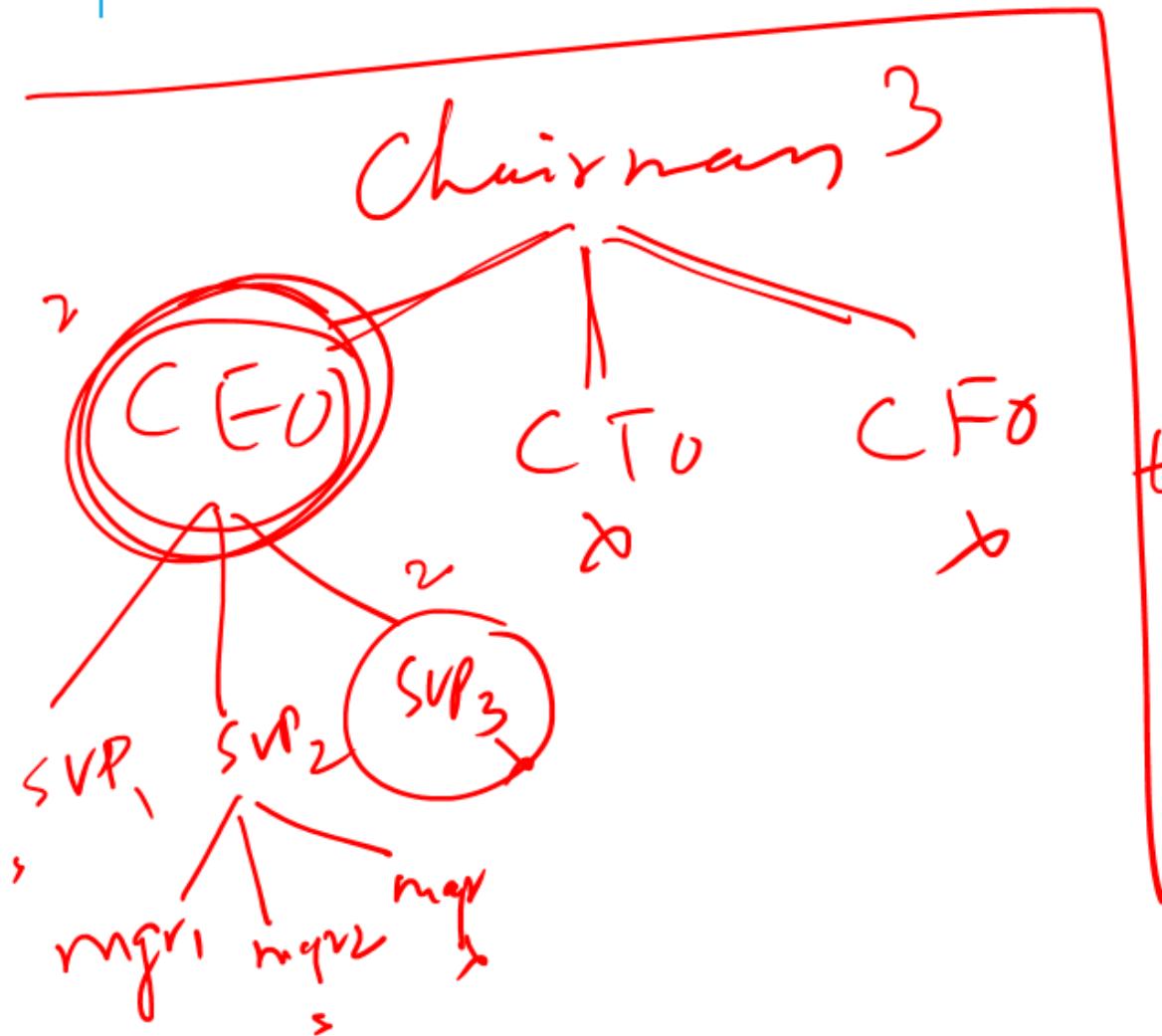
Height of a node and height of tree:  
???

Descendants of a node: ???

What is a sub-tree?      No of edges???

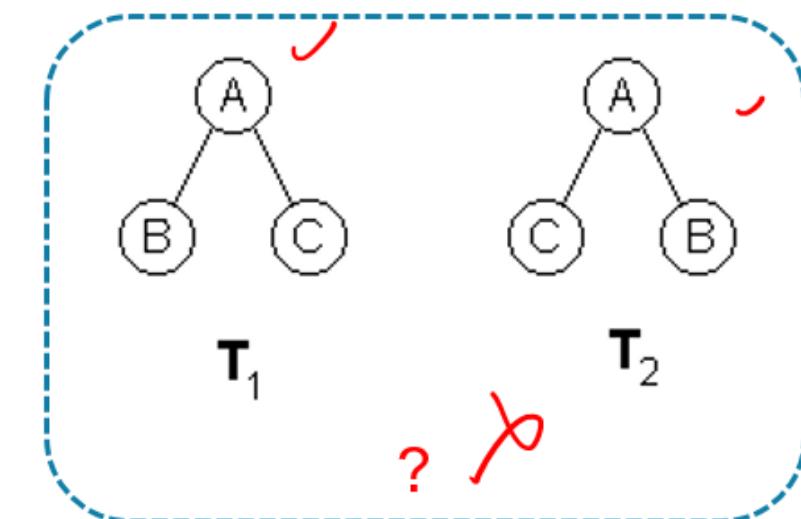
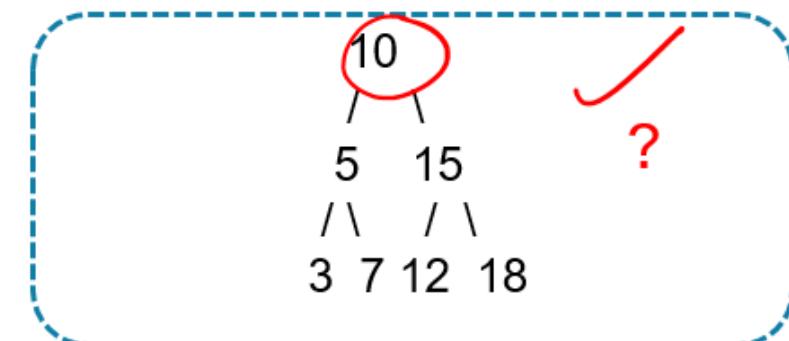
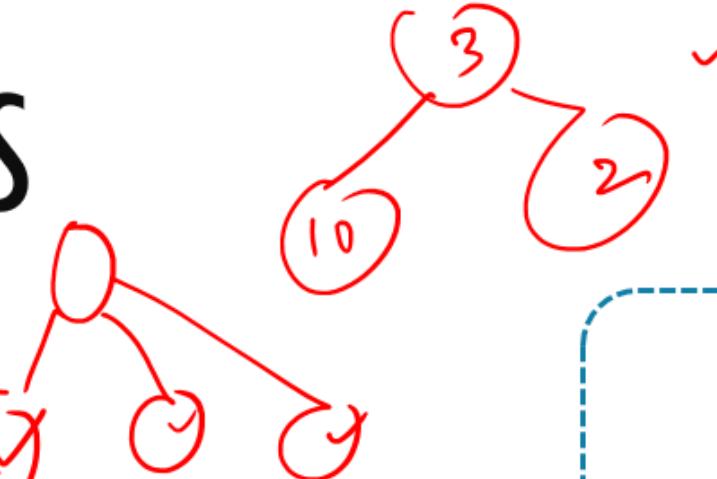
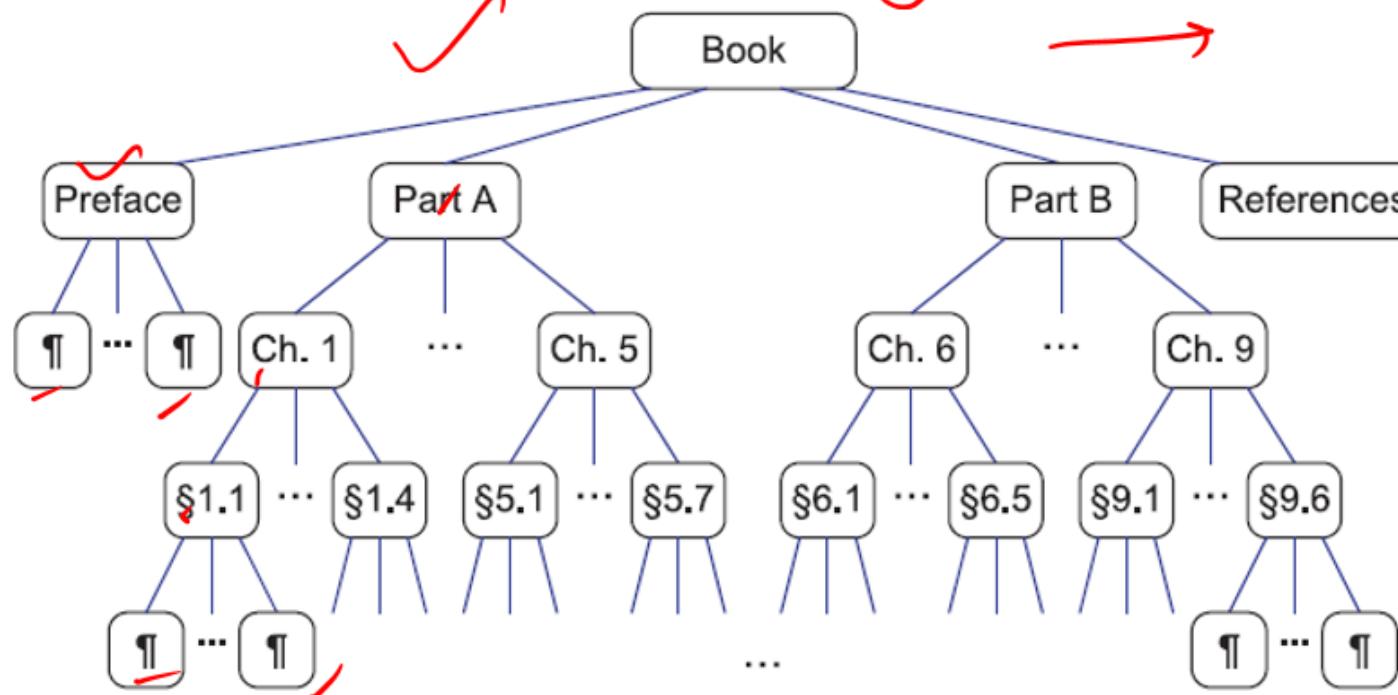


# TRY YOURSELF...

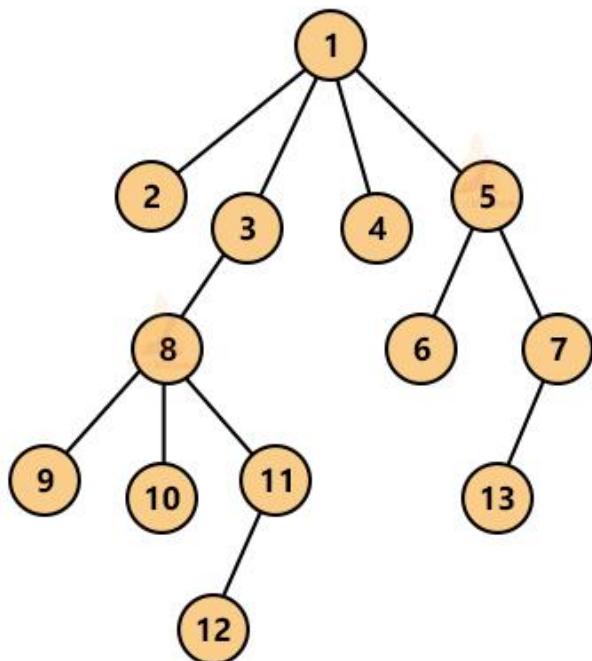


# ORDERED TREES

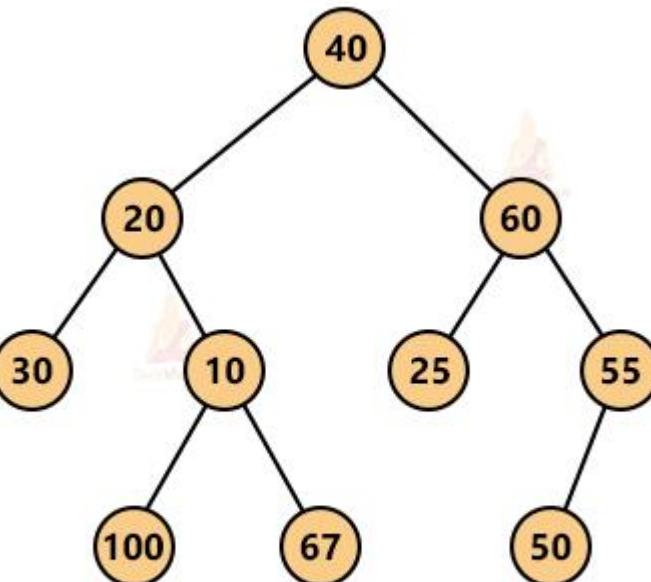
What are Ordered Trees?



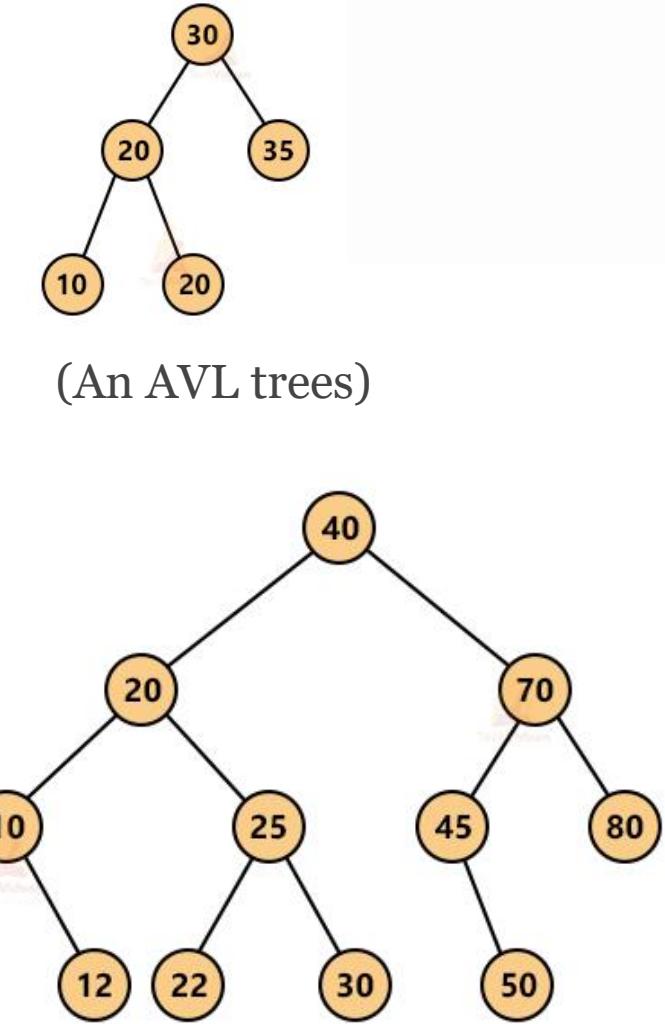
# TYPES OF TREES IN DATA STRUCTURES



(A general tree)



(A binary tree)



(A binary search tree)

# TREE ABSTRACT DATA TYPE (ADT)

- Generic methods:

- integer **size()**
- boolean **empty()**

- Accessor methods:

- position **root()**
- list<position> **positions()**

- Position-based methods:

- position **p.parent()**
- list<position> **p.children()**

- Query methods:

- boolean **p.isRoot()**, boolean **p.isExternal()**

- Additional update methods may be defined by data structures implementing the Tree ADT.

```
template <typename E>
class Position<E> {
public:
    E& operator*();
    Position parent() const;
    PositionList children() const;
    bool isRoot() const;
    bool isExternal() const;
};
```

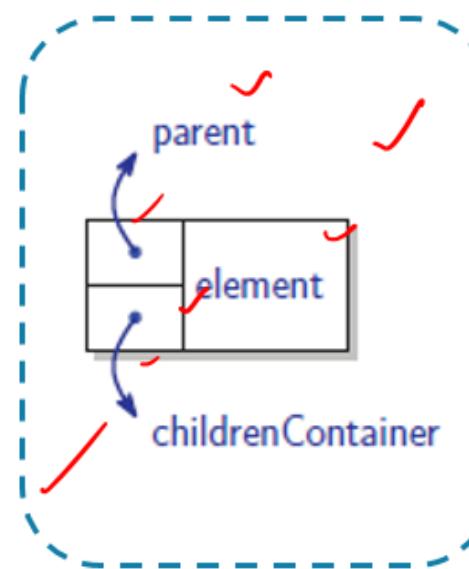
(An informal interface  
for a position in a  
tree)

```
template <typename E>
class Tree<E> {
public:
    class Position;
    class PositionList;
public:
    int size() const;
    bool empty() const;
    Position root() const;
    PositionList positions() const;
};
```

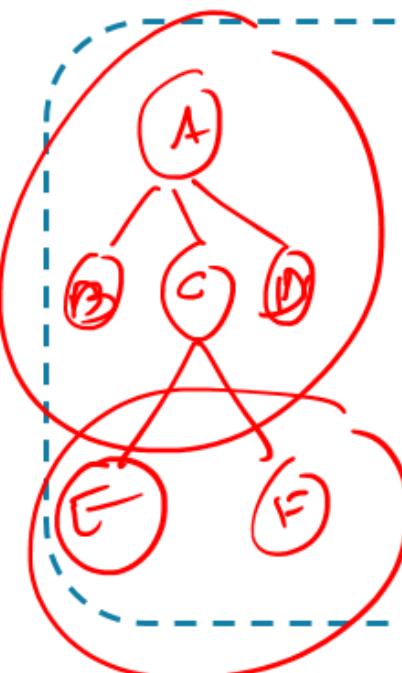
// base element type  
// public types  
// a node position  
// a list of positions  
// public functions  
// number of nodes  
// is tree empty?  
// get the root  
// get positions of all nodes

(An informal interface for the tree ADT)

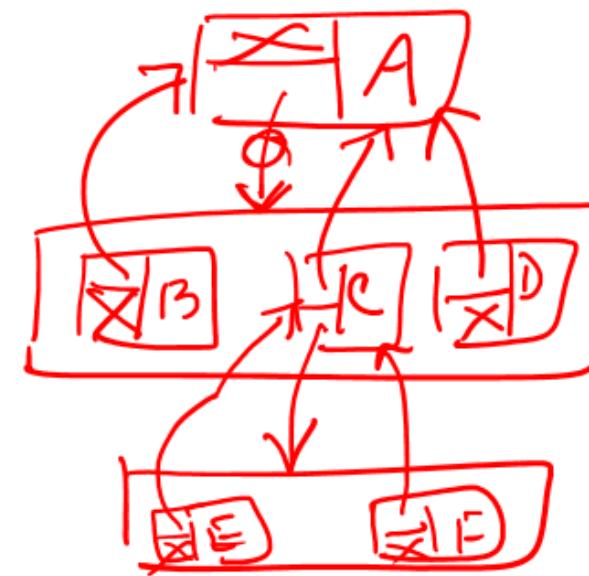
# A LINKED STRUCTURE FOR GENERAL TREES



(The node structure:  
An example)



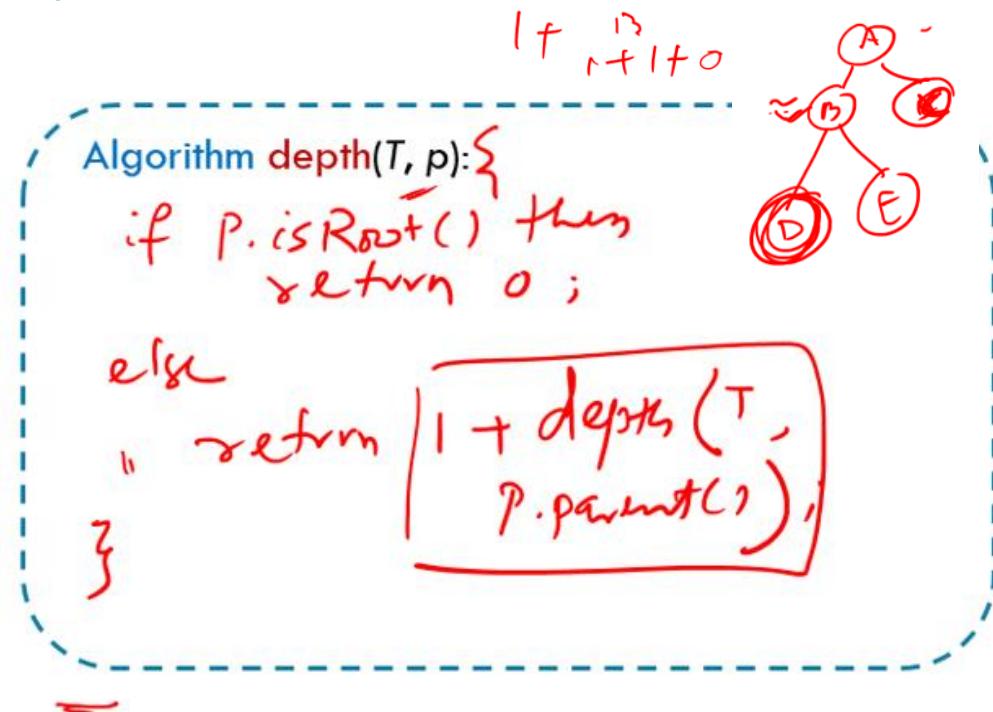
(The portion of the data structure associated  
with root node and its children)



Operation	Time
isRoot, isExternal	$O(1)$
parent	$O(1)$
children( $p$ )	$O(c_p)$
size, empty	$O(1)$
root	$O(1)$
positions	$O(n)$

(Running times of linked  
tree structure)

# DEPTH AND HEIGHT OF NODE IN A TREE



Algorithm `height (T):`

```

h = 0;
for each p ∈ T.positions() do
    if p.isExternal() then
        h = max(h, depth(T, p))
return h

```

$$O\left(n + \sum_{p \in E} (1 + d_p)\right)$$

$$\rightarrow O\left(n + \sum_{p \in E} (1) + \sum_{p \in E} (d_p)\right)$$

$$\begin{array}{c} \downarrow \\ n \end{array} \quad \begin{array}{c} \downarrow \\ 0+1+2+\dots+(n-1) \end{array} \quad \begin{array}{c} \downarrow \\ \frac{n(n-1)}{2} \end{array}$$

$$\rightarrow O(n^2)$$

Run-time Complexity?

- $O(d_p)$  where  $d_p$  is the depth of node  $p$ .
- In worst case,  $d_p$  can be ' $n$ ' and hence worst case complexity is  $O(n)$ .

Algorithm `height(T, p):`

```

if p.isExternal() then
    return 0;
else
    h = 0;
    for each q ∈ p.children() do
        h = max(h, height(T, q))
    return 1+h;

```

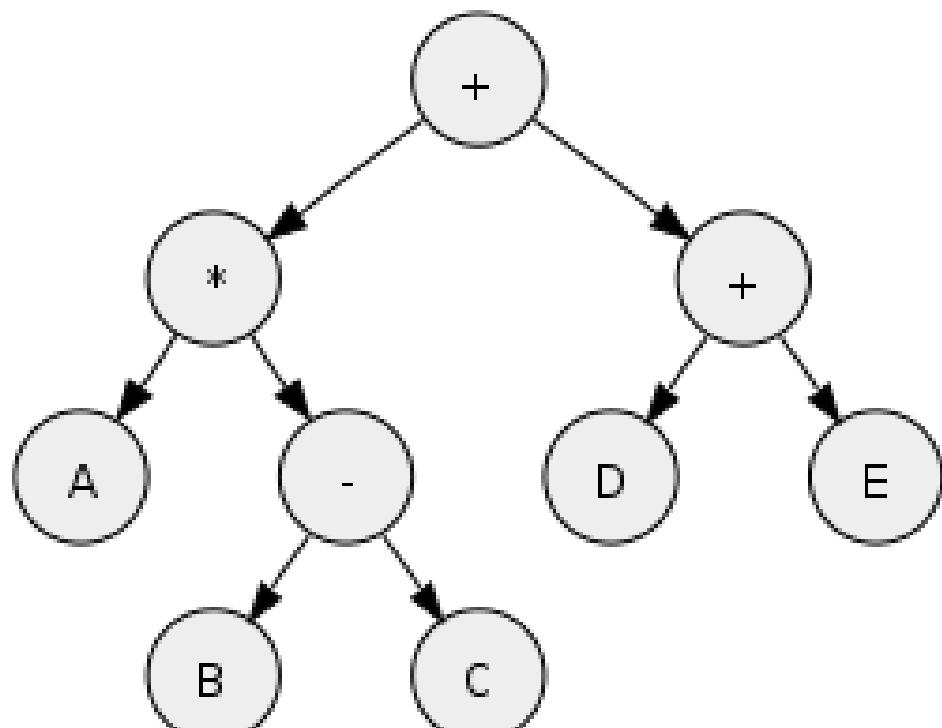
The recursive function spends  $O(1+c_p)$  time at each node  $p$ .

$$O\left(\sum_p (1 + c_p)\right)$$

$$\begin{array}{c} \downarrow \\ \sum_p (1) \end{array} \quad \begin{array}{c} \downarrow \\ \sum_p (c_p) \end{array}$$

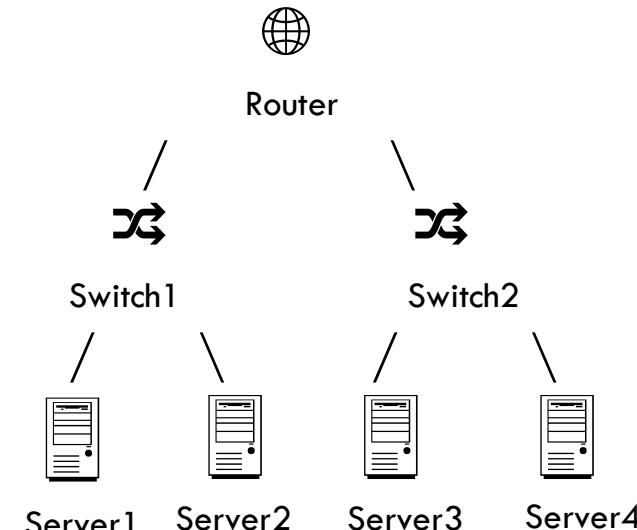
$$\rightarrow O(n)$$

# TREE TRAVERSAL ALGORITHMS



(Expression Tree)

Pre-order: + \* A - B C + D E    Post-order: A B C - \* D E + +



(Network shutdown using **what-order** traversal?)

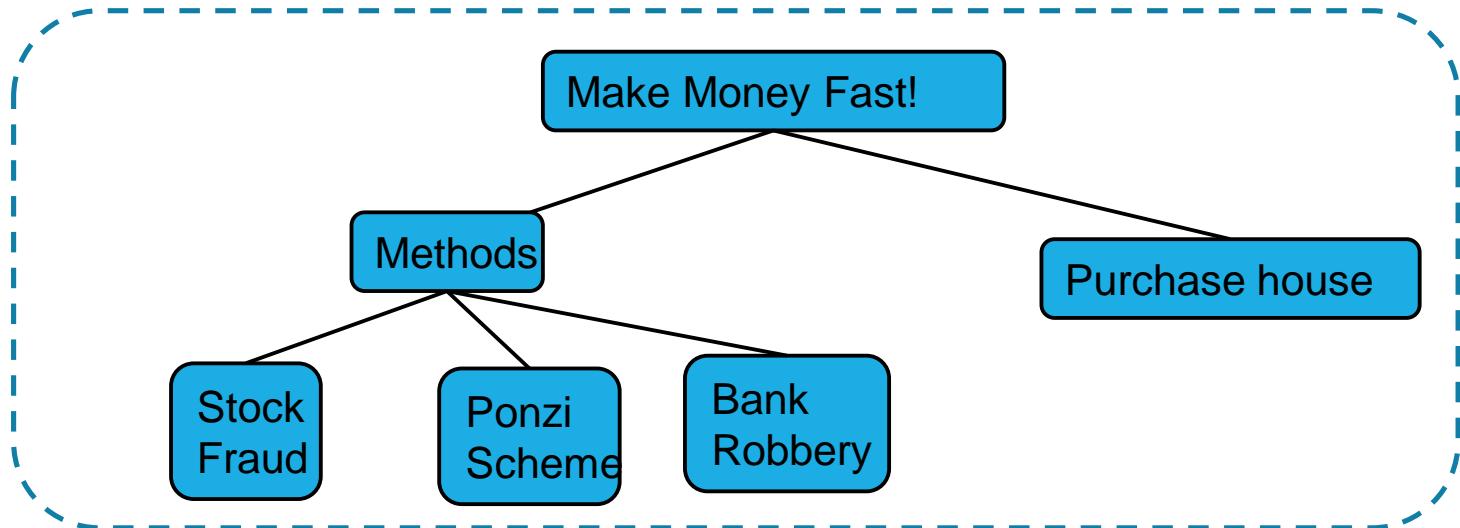
Post order: Server1, Server2, Switch1, Server3, Server4, Switch2, Router.

# TREE TRAVERSAL: DEPTH-FIRST (PRE-ORDER)

- In a preorder traversal, a node is visited **before** its descendants.
- Applications: print a structured document, get the prefix expression on an expression tree.

```
20 void printPreorder(struct Node* node)
21 {
22     if (node == NULL)
23         return;
24     cout << node->data << " ";
25     printPreorder(node->left);
26     printPreorder(node->right);
27 }
```

Preorder traversal of binary tree is  
1 2 4 5 3



Algorithm *preOrder* ( $T, p$ )  
{ visit ( $p$ );  
preorder( $p \rightarrow \text{left}$ );  
preorder( $p \rightarrow \text{right}$ );  
}

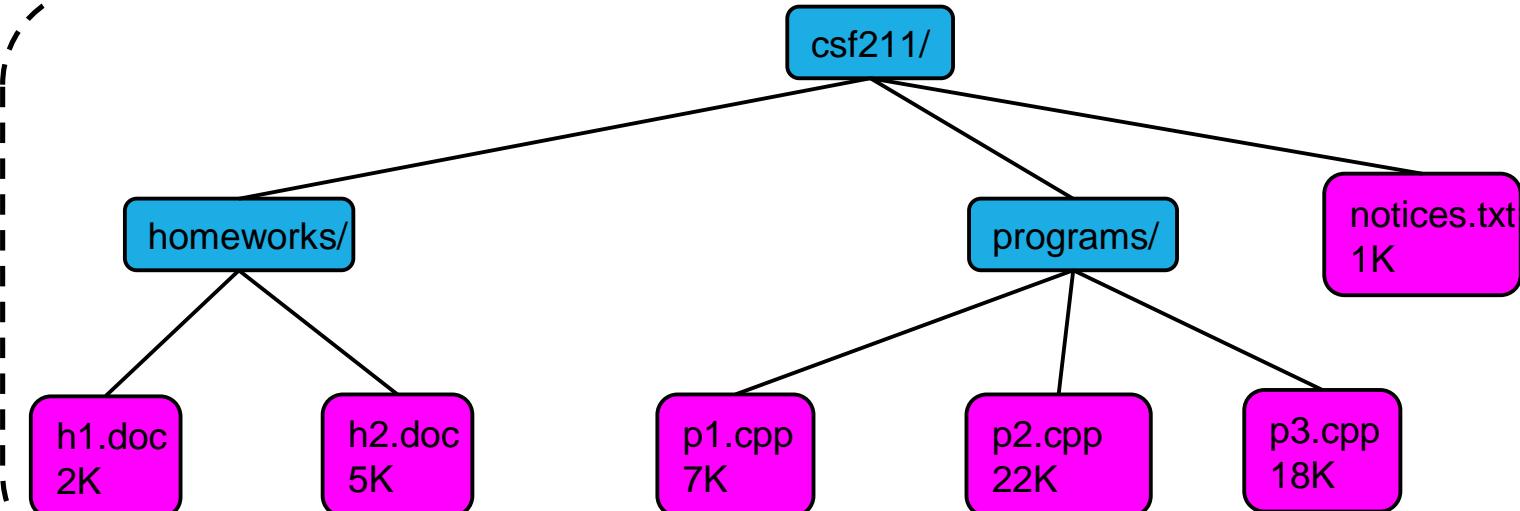
← Lab 8 after mid sem

```
PreOrderIterative(root){  
if (root == NULL)  
    return;  
Create stack S=Φ; Push N.right;  
Push root to S; if (N.left ≠ NULL)  
While Stack S ≠ Φ { Push N.left; }  
    N=Pop from S;  
    Print N.value;
```

# POST-ORDER TRAVERSAL

- In a postorder traversal, a node is visited after its descendants.
- Application: compute space used by files in a directory and its subdirectories, delete the tree, compute postfix expression...

```
Algorithm postOrder(v){  
for each child w of v  
    postOrder (w);  
visit(v);  
}
```



```
23 void printPostorder(struct Node* node)  
24 {  
25     if (node == NULL)  
26         return;  
27  
28     printPostorder(node->left);  
29     printPostorder(node->right);  
30     cout << node->data << " ";  
31  
32 }  
33 }
```

Lab 8 after mid sem

```
Postorder traversal of binary tree is  
4 5 2 3 1
```

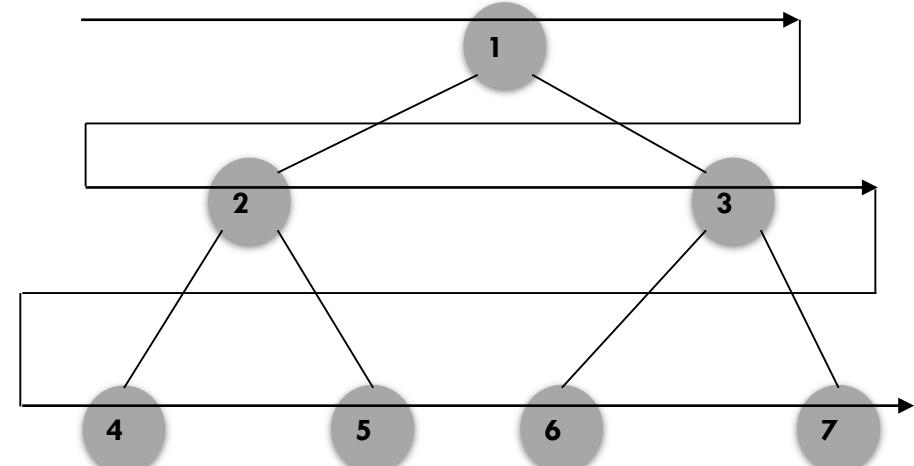
# TREE TRAVERSAL CONTINUED... LEVEL ORDER

```
LevelOrderTraversal(root) {  
    if (root == NULL) then  
        return;  
    Q  $\leftarrow \emptyset$   
    Enqueue (root);  
    while (Q  $\neq \emptyset$ ) {  
        node = Dequeue from Q;  
        Print node.value // Process the current node  
        if node.left  $\neq \emptyset$   
            Enqueue node.left into Q;  
        if node.right  $\neq \emptyset$   
            Enqueue node.right into Q;  
    }  
}
```

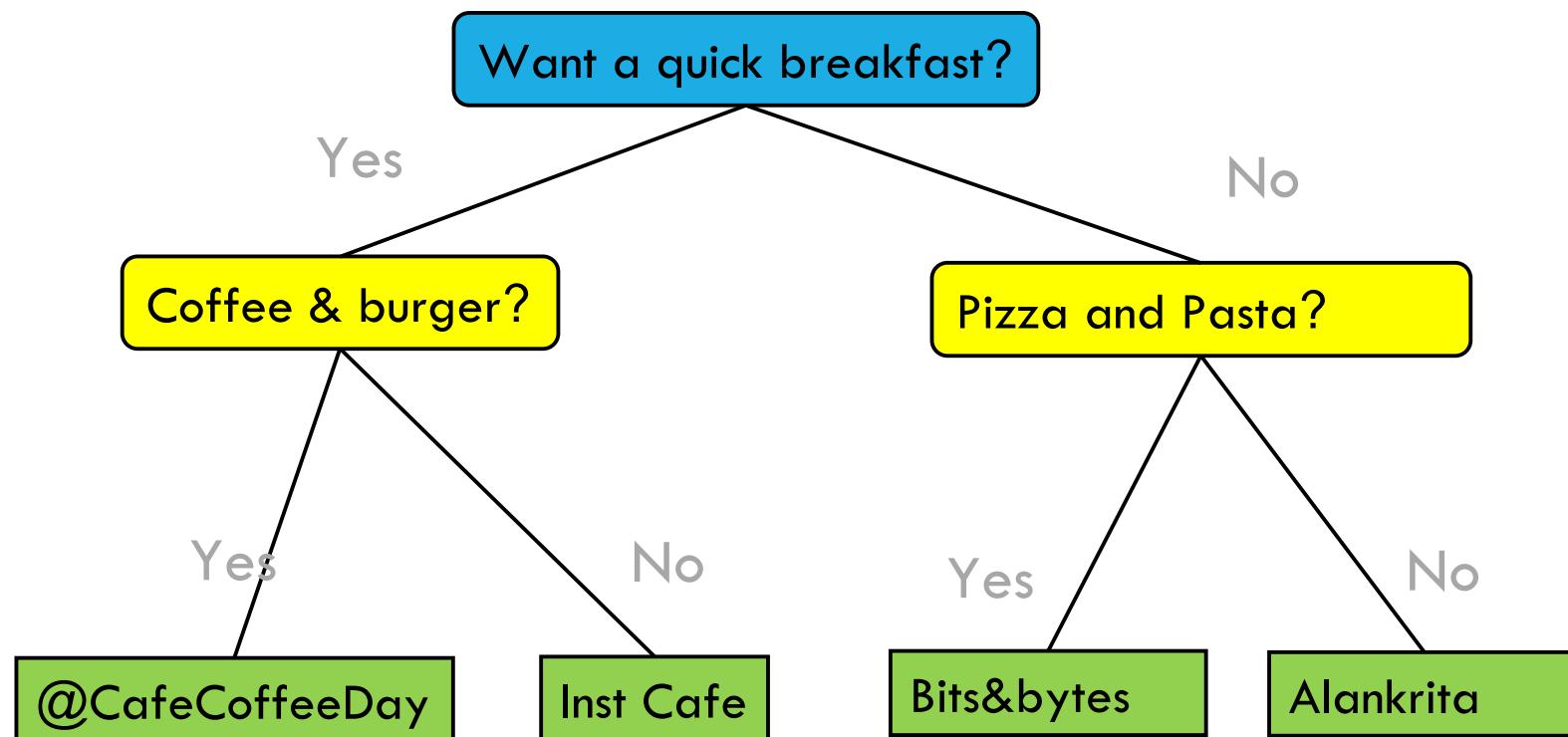
## Application:

Construct a binary tree from an array using a level-order traversal:

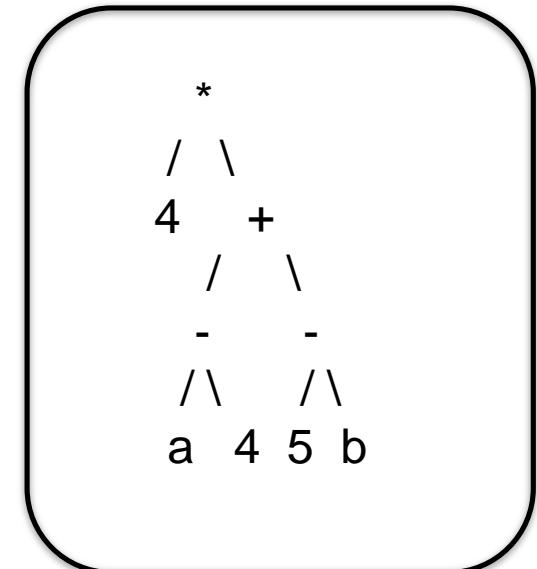
Let the array be: Arr = [1, 2, 3, 4, 5, 6, 7]



# BINARY TREES: EXAMPLE USAGES

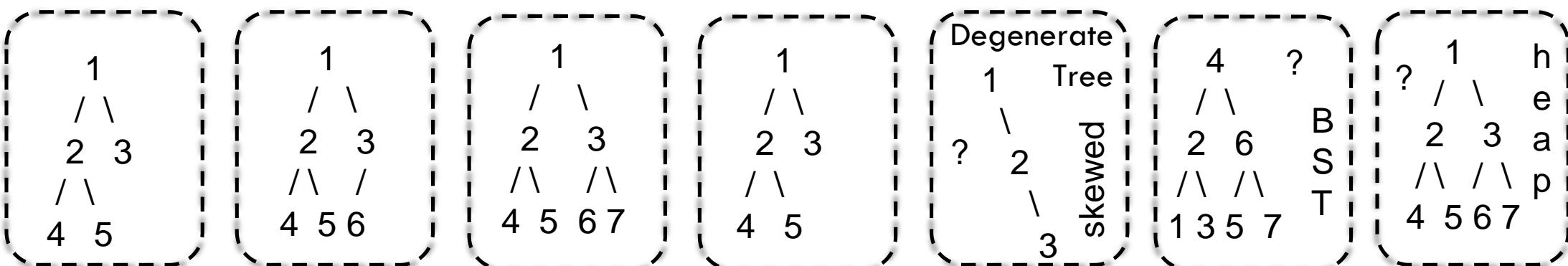
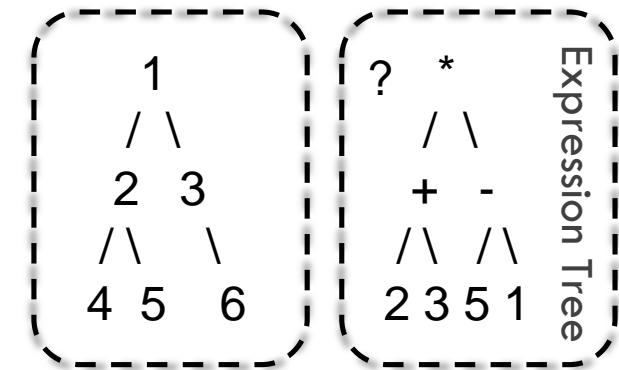


Expression Tree:  
 $4 \times ((a - 4) + (5 - b))$



# DEFINITIONS: BINARY TREE

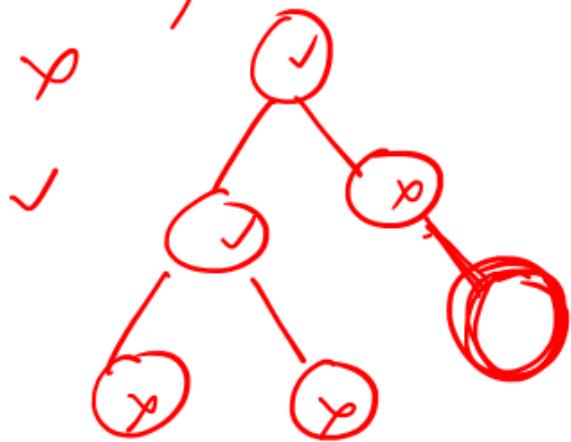
- A hierarchical data structure in which each node has **at most** two children.
- **Full Binary Tree:** Every node has either 0 or 2 children.
- **Complete Binary Tree:** All levels are fully filled except possibly the last level, which is filled from left to right.
- **Perfect Binary Tree:** All interior nodes have exactly two children, and all leaves are at the same depth.
- **Balanced Binary Tree:** The height of the left and right subtrees of every node differs by no more than 1.



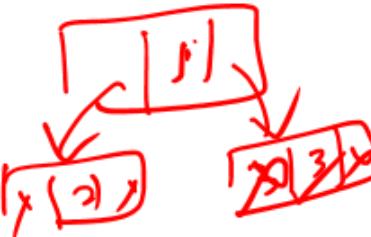
# BINARY TREES: TRY YOURSELF!

~~not~~

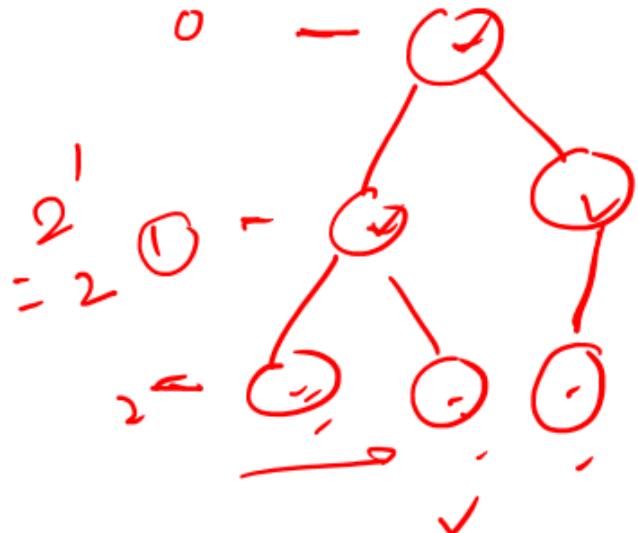
full binary tree



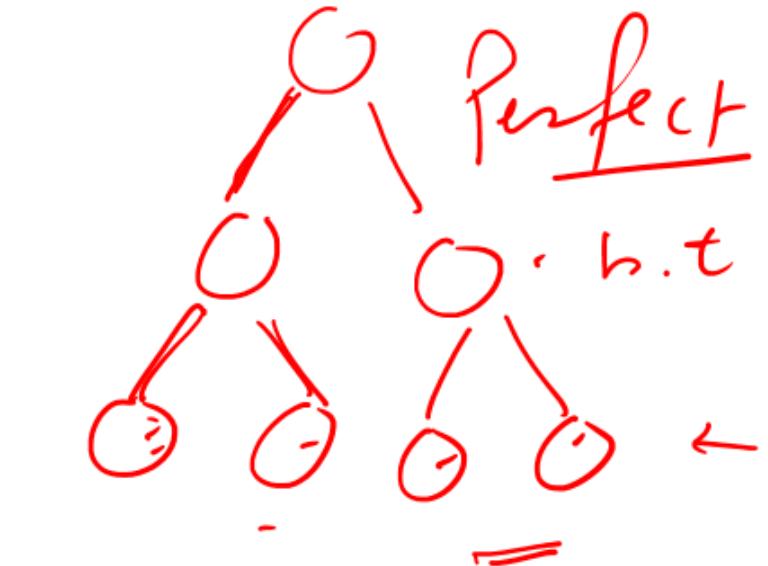
full b.t. ✅



Complete b.t



Complete b.t



Perfect

b.t.

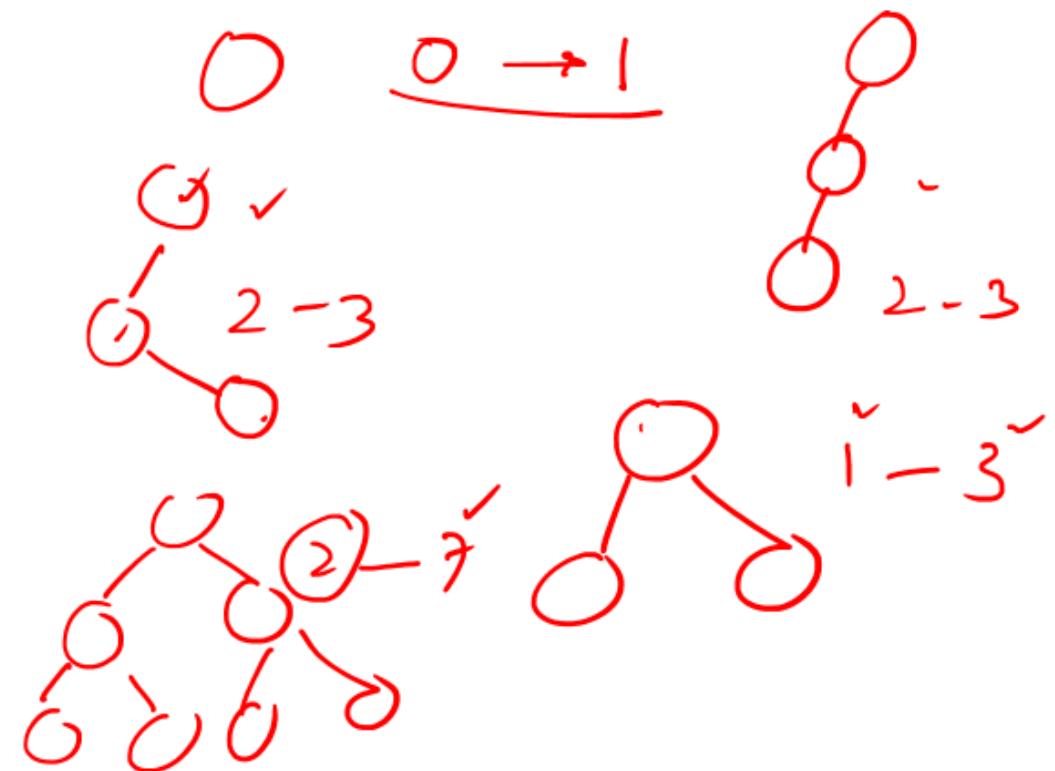
# PROPERTIES OF A BINARY TREE



Notation:

**n**: number of nodes, **e**: number of external nodes, **i**: number of internal nodes, and **h**: height

- Minimum number of nodes in a binary tree with height  $h$  = ?  $h+1$
- Maximum number of nodes in a binary tree with height  $h$  = ?  $2^{h+1}-1$
- Total number of leaf nodes in a binary tree = ? Nodes with 2 children + 1
- Maximum number of nodes at any level ' $l$ ' in a binary tree = ?  $2^l$

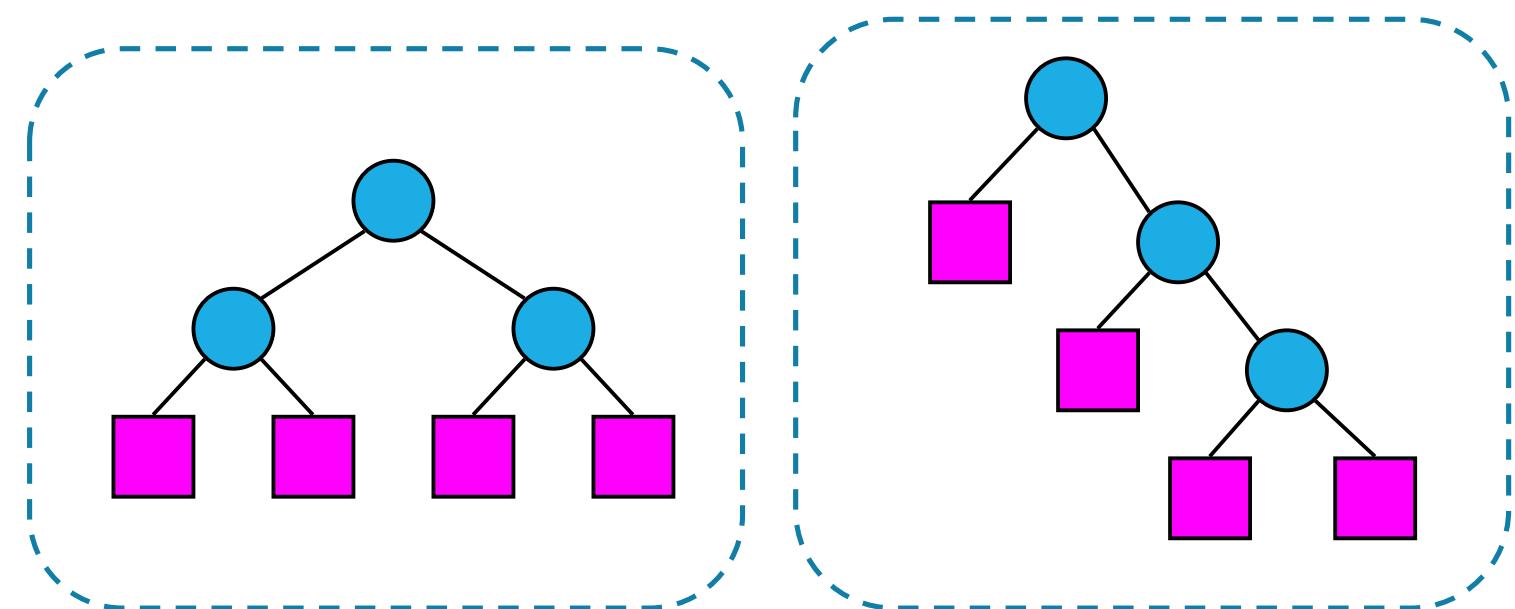


# CONTINUED...

## Notation:

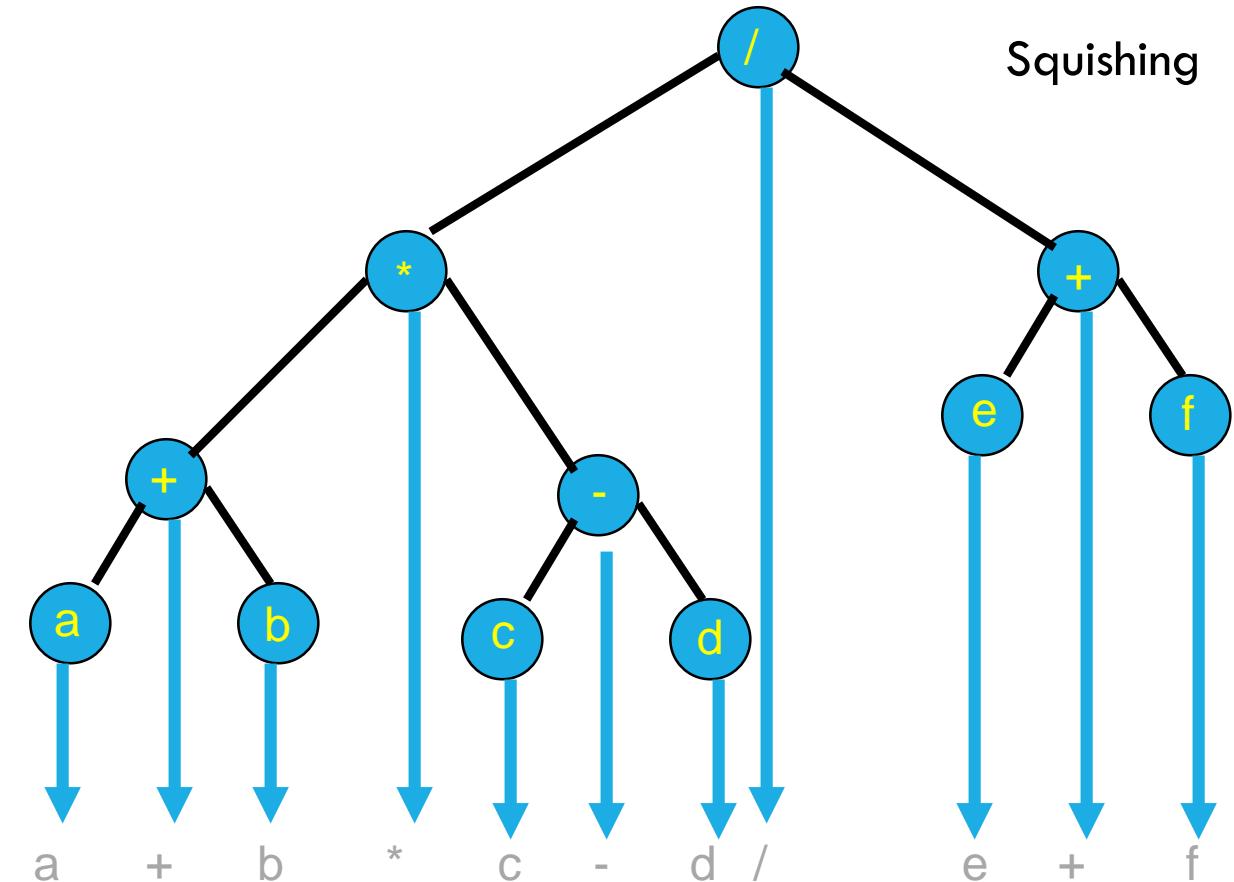
$n$ : number of nodes,  $e$ : number of external nodes,  $i$ : number of internal nodes, and  $h$ : height

- Properties:
  - $e = i + 1$
  - $n = 2e - 1$
  - $h \leq i$
  - $h \leq (n - 1)/2$
  - $e \leq 2^h$
  - $h \geq \log_2 e$
  - $h \geq \log_2 (n + 1) - 1$



# BINARY TREE TRAVERSAL: IN-ORDER

```
template <class T>
void inOrder(binaryTreeNode<T> *t)
{
    if (t != NULL)
    {
        inOrder(t->leftChild);
        visit(t);
        inOrder(t->rightChild);
    }
}
```



Lab: after midterm (Lab no:8)

Gives infix form of expression!

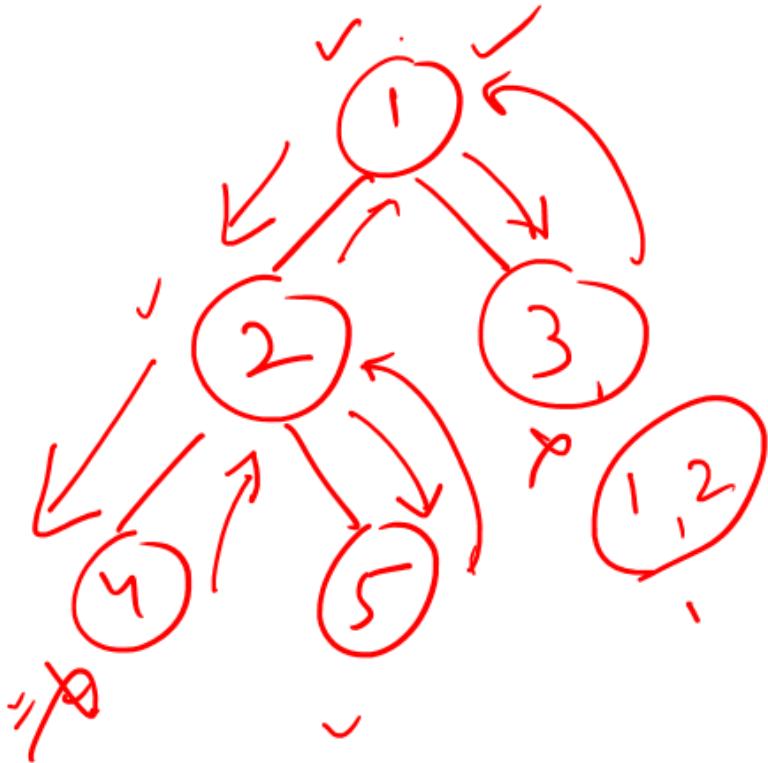
1 - 2 - 4      1 - 3

1 -  $\binom{2}{2}$  - 4  
1 -  $\binom{2}{2}$  - 5

$\frac{9-1+1}{2}$

## EULER TOUR TRAVERSAL: GENERIC

Applications: finding ancestor, LCA (lowest common ancestor), finding number of descendants, etc.



1, 2, 4, 2, 5, 2, 1, 3, 1

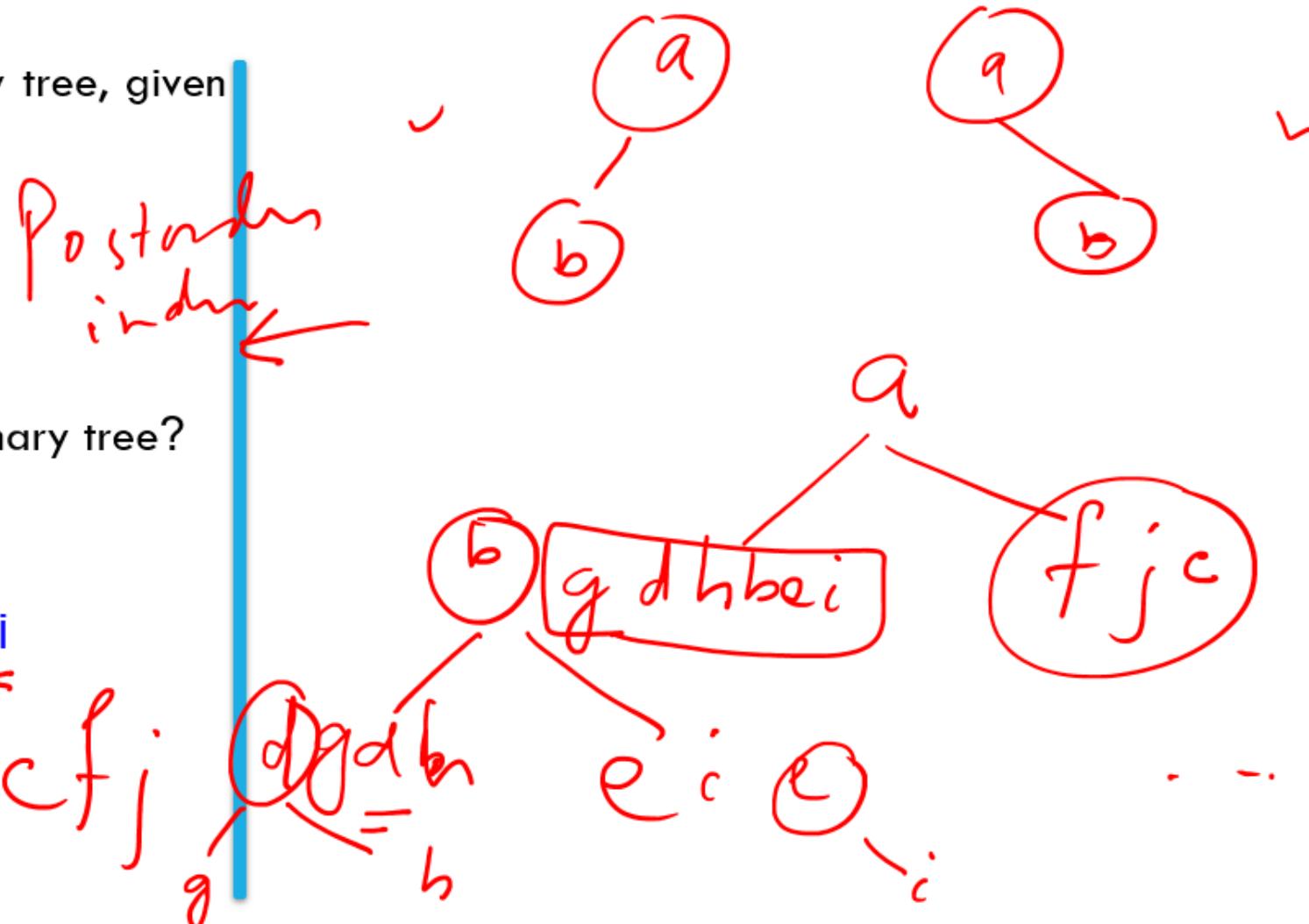
+in      +in-  
1 → 1      1  
2 → 2      6  
3 → 8      8  
4 → 3      3  
5 → 5      5

tin(A) { tin(B)  
tin(A) > tin(B)

# BINARY TREE CONSTRUCTION FROM TRAVERSAL ORDER

Can you construct the binary tree, given two traversal sequences?

preorder = a b //  
postorder = b a



do they uniquely define a binary tree?

inorder = g d h b e i a f j c  
preorder = a b d g h e i c f j

Try:

Postorder: DEBFCA

Inorder: DBEAFC

D g h e i c f j

# BINARY TREE ADT

- p.left()*: Return the left child of *p*; an error condition occurs if *p* is an external node.
- p.right()*: Return the right child of *p*; an error condition occurs if *p* is an external node.
- p.parent()*: Return the parent of *p*; an error occurs if *p* is the root.
- p.isRoot()*: Return true if *p* is the root and false otherwise.
- p.isExternal()*: Return true if *p* is external and false otherwise.
- size()*: Return the number of nodes in the tree.
- empty()*: Return true if the tree is empty and false otherwise.
- root()*: Return a position for the tree's root; an error occurs if the tree is empty.
- positions()*: Return a position list of all the nodes of the tree.

```
template <typename E>
class Position<E> {
```

**public:**

```
E& operator*();
Position left() const;
Position right() const;
Position parent() const;
bool isRoot() const;
bool isExternal() const;
```

};

```
template <typename E>
```

```
class BinaryTree<E> {
```

**public:**

```
class Position;
class PositionList;
```

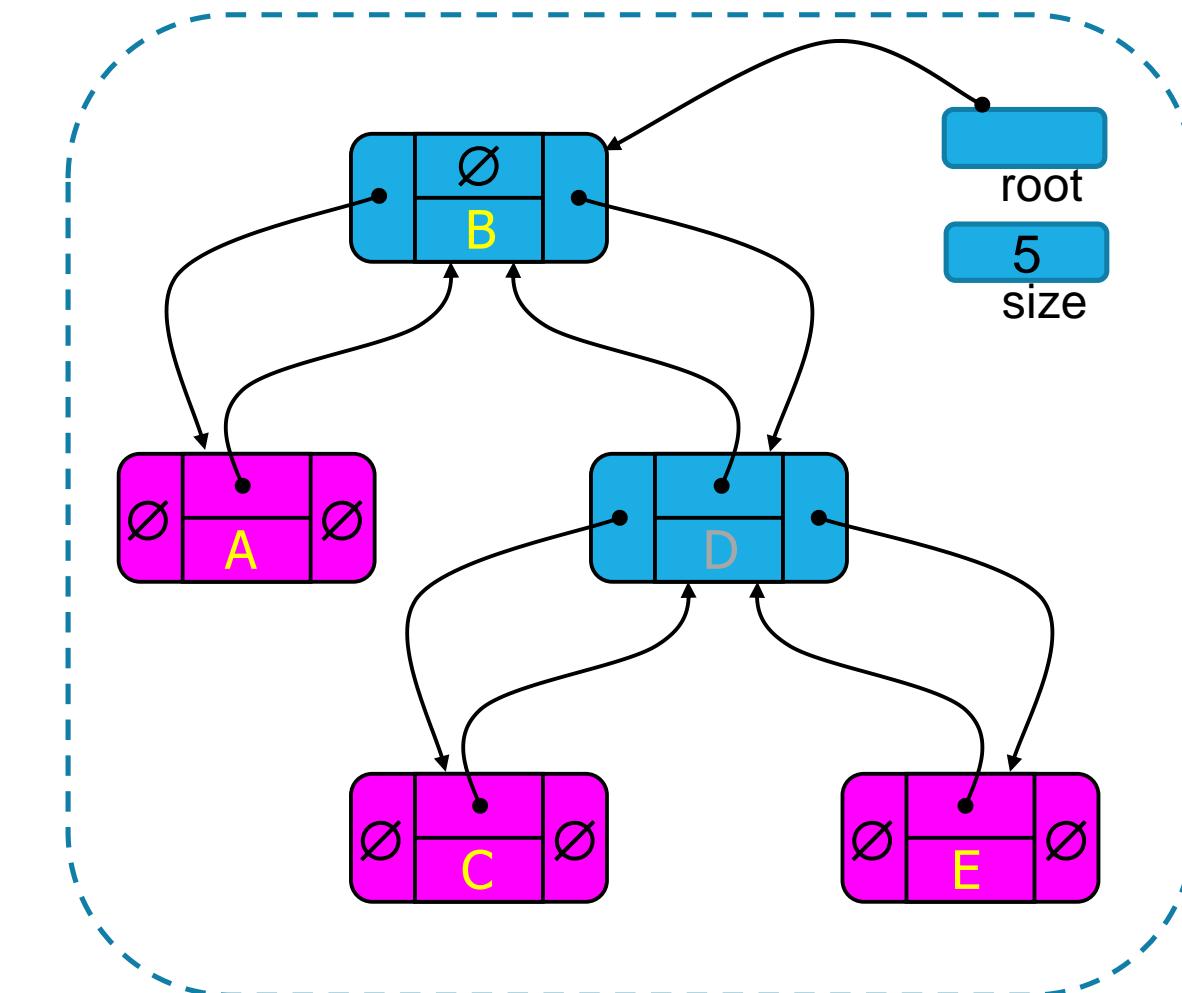
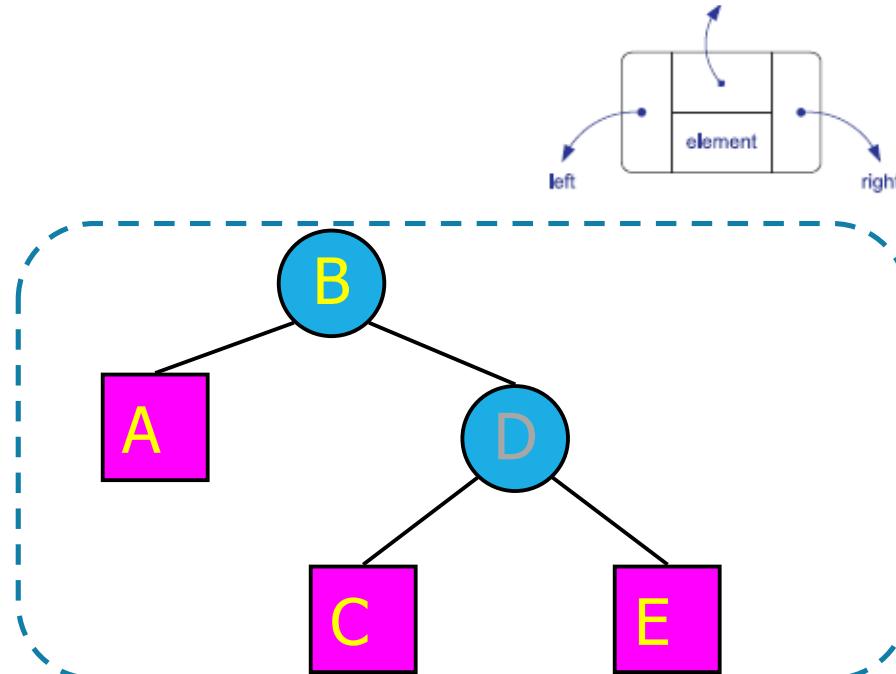
**public:**

```
int size() const;
bool empty() const;
Position root() const;
PositionList positions() const;
```

};

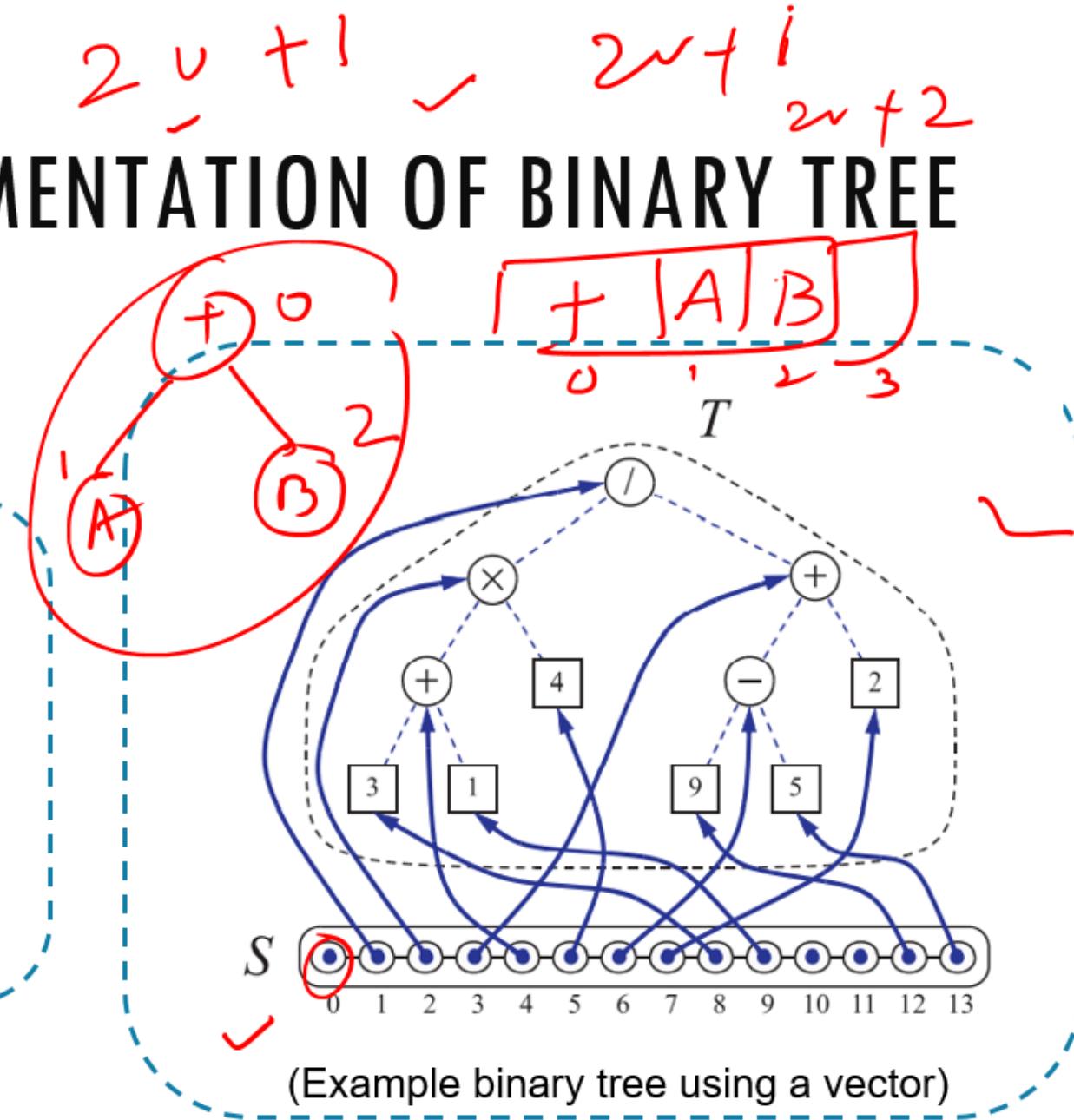
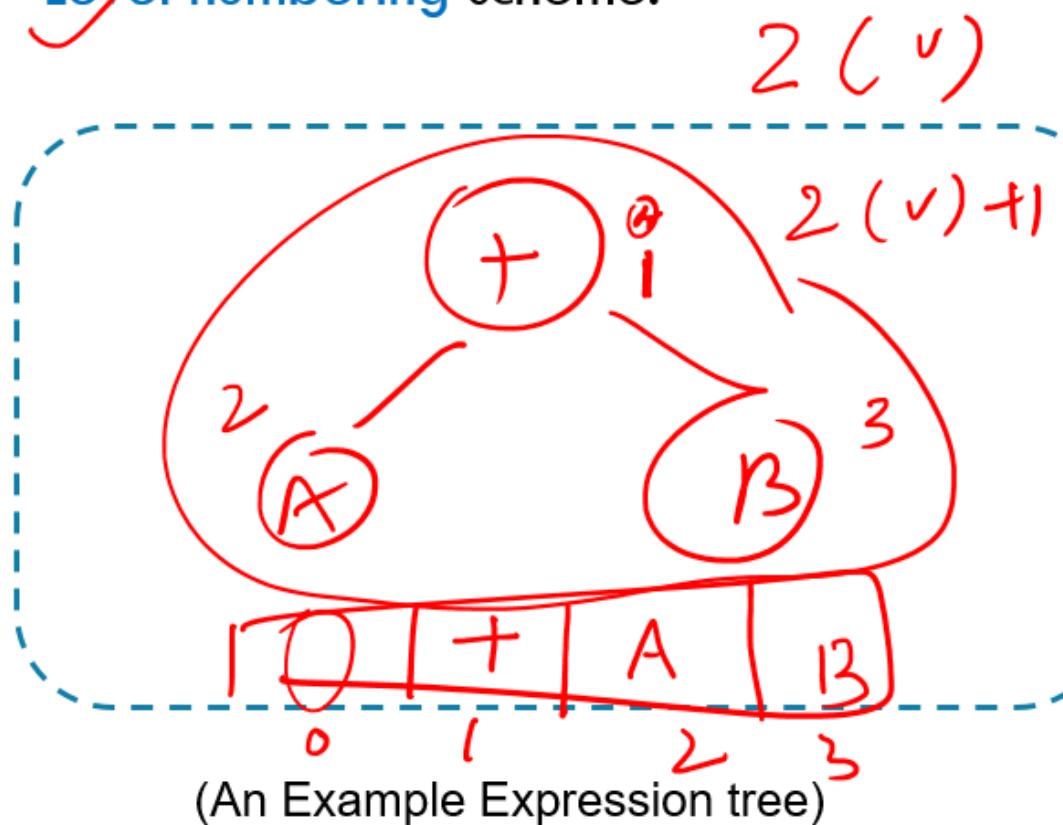
# LINKED STRUCTURE FOR BINARY TREES

```
struct Node{  
    Node *left;  
    Node *right;  
    Node *par;  
    int data;  
    Node() : data(), par(NULL), left(NULL), right(NULL) { }  
};
```

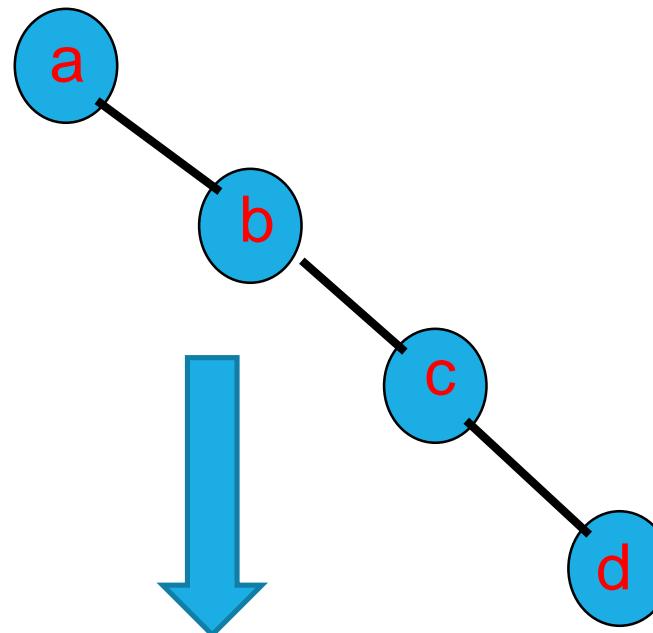
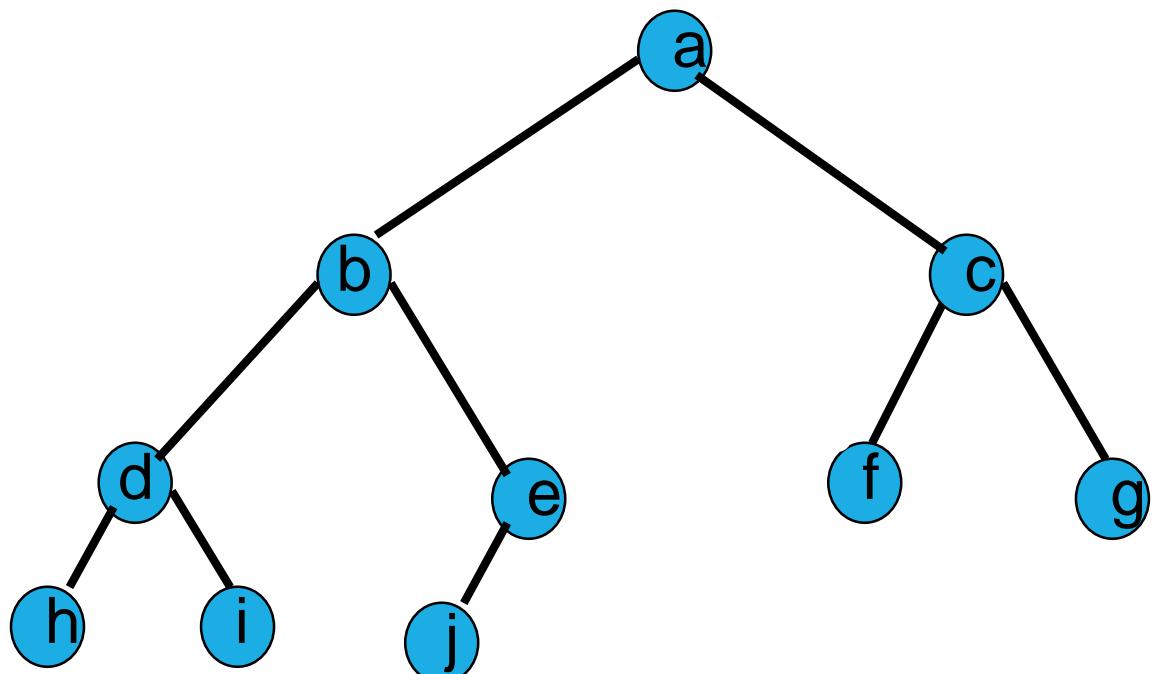


# A VECTOR-BASED IMPLEMENTATION OF BINARY TREE

- Level numbering scheme.



# TRY YOURSELF...



tree[ ] a b c d e f g h i j

0 a - b - - c - - - - - d 15

tree[ ]

# BINARY TREE IMPLEMENTATION USING LINKED STRUCT

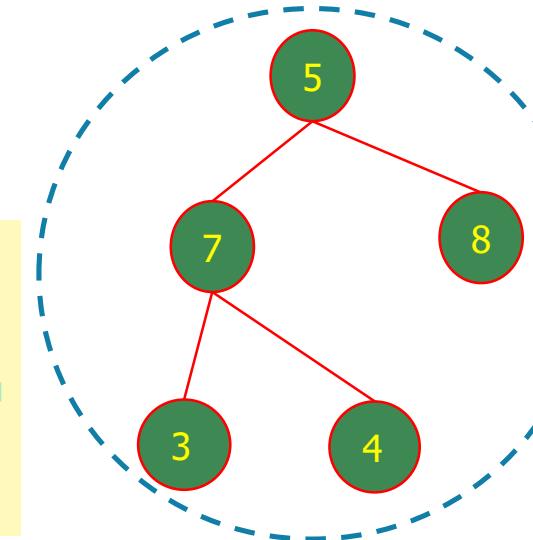
```
77 void BinaryTree::inorder(Node *ptr){  
78     if(!ptr) return;  
79     inorder(ptr->left);  
80     cout<< " "<<ptr->data;  
81     inorder(ptr->right);  
82 }  
83 void BinaryTree::postorder(Node *ptr){  
84     if(!ptr) return;  
85     postorder(ptr->left);  
86     postorder(ptr->right);  
87     cout<< " "<<ptr->data;  
88 }  
89 void BinaryTree::preorder(Node *ptr){  
90     if(!ptr) return;  
91     cout<<ptr->data<< " ";  
92     preorder(ptr->left);  
93     preorder(ptr->right);  
94 }
```

`expandExternal(const Position& p)`

```
void LinkedBinaryTree::expandExternal(const Position& p) {  
    Node* v = p.v;  
    v->left = new Node;  
    v->left->par = v;  
    v->right = new Node;  
    v->right->par = v;  
    n += 2;  
}  
  
// expand external node  
// p's node  
// add a new left child  
// v is its parent  
// and a new right child  
// v is its parent  
// two more nodes
```

```
98 Node* BinaryTree::createTree(vector<int> &v,Node *root,  
99                               Node *parent,int i){  
100    ...  
101    n = v.size();  
102    if(i<v.size()){  
103        Node *temp = new Node;  
104        temp->data = v[i];  
105        temp->par = parent;  
106        root = temp;  
107        root->left = createTree(v,root->left,root,2*i+1);  
108        root->right = createTree(v,root->right,root,2*i+2);  
109        all_nodes.insert(root);  
110    }  
111    main_root = root;  
112    ...  
...}
```

Lab 9



```
Enter size of input array : 6  
Enter array : 5 7 8 3 4 9  
1  
Size : 6  
2  
Tree is not empty  
3  
Inorder traversal : 3 7 4 5 9 8  
4  
Preorder traversal : 5 7 3 4 8 9  
5  
Postorder traversal : 3 4 7 9 8 5  
6  
Height by height1 : 2  
7  
Height by height2 : 2
```

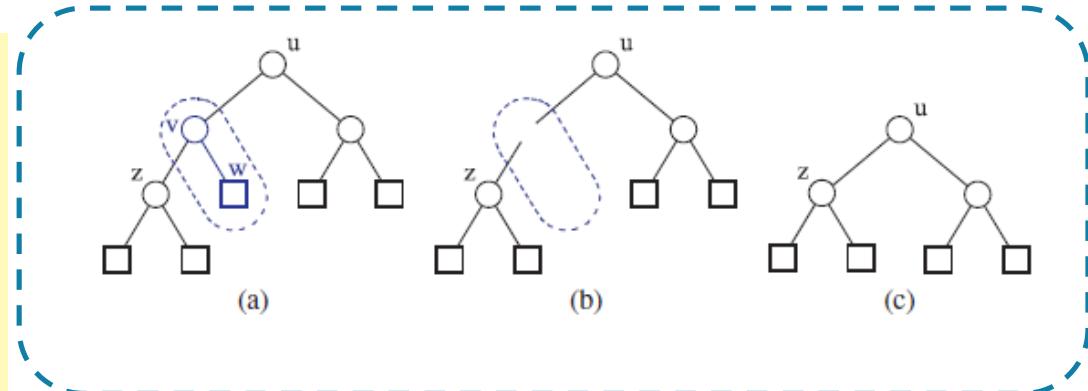
```
Enter size of input array : 5  
Enter array : 5 7 8 3 4  
1  
Size : 5  
2  
Tree is not empty  
3  
Inorder traversal : 3 7 4 5 8  
4  
Preorder traversal : 5 7 3 4 8  
5  
Postorder traversal : 3 4 7 8 5  
6  
Height by height1 : 2  
7  
Height by height2 : 2
```

# BINARY TREE UPDATE FUNCTIONS

removeAboveExternal (const Position& p)

```
LinkedBinaryTree::Position removeAboveExternal(const Position& p) {  
    Node* w = p.v(); Node* v = w->par;  
    Node* sib = (w == v->left ? v->right : v->left);  
    if (v == _root) {  
        _root = sib;  
        sib->par = NULL;  
    }  
    else {  
        Node* gpar = v->par;  
        if (v == gpar->left) gpar->left = sib;  
        else gpar->right = sib;  
        sib->par = gpar;  
    }  
    delete w; delete v;  
    n -= 2;  
    return Position(sib);  
}
```

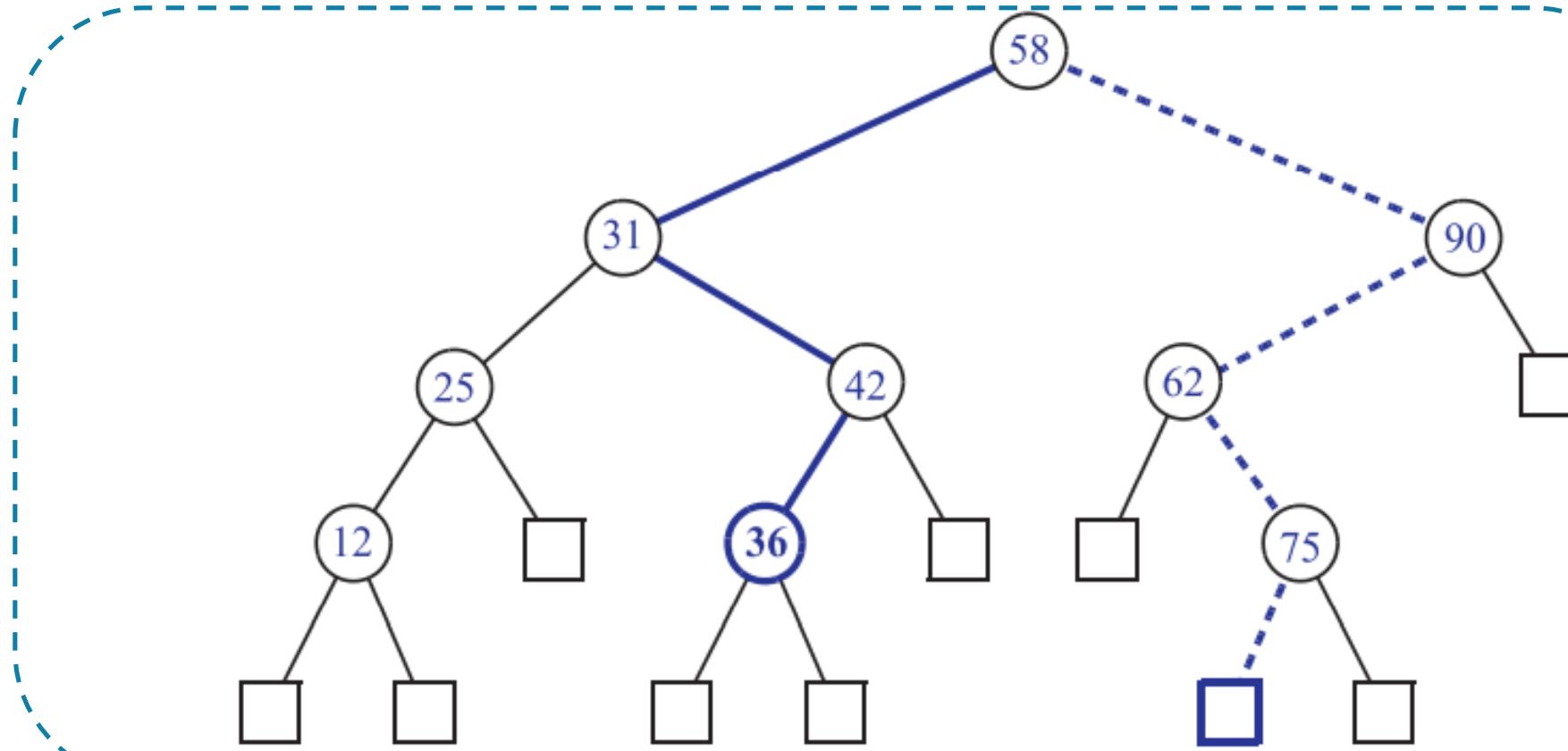
// remove p and parent  
// get p's node and parent  
// child of root?  
// ...make sibling root  
// w's grandparent  
// replace parent by sib  
// delete removed nodes  
// two fewer nodes



The vector implementation of a binary tree is a fast and easy way of realizing the binary-tree ADT, but it can be very space inefficient if the height of the tree is large.  $\Rightarrow O(2^n)$ , where 'n' is no. of nodes in T.

Operation	Time
left, right, parent, isExternal, isRoot	$O(1)$
size, empty	$O(1)$
root	$O(1)$
expandExternal, removeAboveExternal	$O(1)$
positions	$O(n)$

# BINARY SEARCH TREE (BST)



(Searching successfully 36 through blue solid path, and unsuccessfully 71 through dashed path)

More later  
...

# THE TEMPLATE FUNCTION PATTERN

- The template function pattern describes a generic computation method that can be tuned for a particular application by redefining certain steps.

```
template <typename E, typename R>           // element and result types
class EulerTour {                         // a template for Euler tour
protected:
    struct Result {                      // stores tour results
        R leftResult;                   // result from left subtree
        R rightResult;                 // result from right subtree
        R finalResult;                 // combined result
    };
    typedef BinaryTree<E> BinaryTree;      // the tree
    typedef typename BinaryTree::Position Position; // a position in the tree
protected:
    const BinaryTree* tree;               // data member
public:
    void initialize(const BinaryTree& T)   // initialize
    { tree = &T; }
protected:
    int eulerTour(const Position& p) const; // perform the Euler tour
                                                // functions given by subclasses
    virtual void visitExternal(const Position& p, Result& r) const {};
    virtual void visitLeft(const Position& p, Result& r) const {};
    virtual void visitBelow(const Position& p, Result& r) const {};
    virtual void visitRight(const Position& p, Result& r) const {};
    Result initResult() const { return Result(); }
    int result(const Result& r) const { return r.finalResult; }
};
```

```
template <typename E, typename R>           // do the tour
int EulerTour<E, R>::eulerTour(const Position& p) const {
    Result r = initResult();
    if (p.isExternal()) {                  // external node
        visitExternal(p, r);
    } else {                                // internal node
        visitLeft(p, r);
        r.leftResult = eulerTour(p.left());   // recurse on left
        visitBelow(p, r);
        r.rightResult = eulerTour(p.right()); // recurse on right
        visitRight(p, r);
    }
    return result(r);
}
```

(Class `EulerTour` defining a generic Euler tour of a binary tree. It realizes **template function pattern** and must be specialized for use)

(Member function `eulerTour` recursively traverses the tree and accumulates the results)

# CONTINUED...

```
template <typename E, typename R>
class EvaluateExpressionTour : public EulerTour<E, R> {
protected: // shortcut type names
    typedef typename EulerTour<E, R>::BinaryTree BinaryTree;
    typedef typename EulerTour<E, R>::Position Position;
    typedef typename EulerTour<E, R>::Result Result;
public:
    void execute(const BinaryTree& T) { // execute the tour
        initialize(T);
        std::cout << "The value is: " << eulerTour(T.root()) << "\n";
    }
protected: // leaf: return value
    virtual void visitExternal(const Position& p, Result& r) const
    { r.finalResult = (*p).value(); } // internal: do operation
    virtual void visitRight(const Position& p, Result& r) const
    { r.finalResult = (*p).operation(r.leftResult, r.rightResult); }
};
```

(Implementation of class `EvaluateExpressionTour` which specializes `EulerTour` to evaluate the expression associated with an arithmetic expression tree)

```
template <typename E, typename R>
class PrintExpressionTour : public EulerTour<E, R> {
protected: // ...same type name shortcuts as in EvaluateExpressionTour
public:
    void execute(const BinaryTree& T) { // execute the tour
        initialize(T);
        cout << "Expression: " << eulerTour(T.root()); cout << endl;
    }
protected: // leaf: print value
    virtual void visitExternal(const Position& p, Result& r) const
    { (*p).print(); } // left: open new expression
    virtual void visitLeft(const Position& p, Result& r) const
    { cout << "("; } // below: print operator
    virtual void visitBelow(const Position& p, Result& r) const
    { (*p).print(); } // right: close expression
    virtual void visitRight(const Position& p, Result& r) const
    { cout << ")"; }
};
```

(A derived class, called `PrintExpressionTour` that prints the arithmetic expression)

# THANK YOU!

Next class: Priority Queues, and Heaps...